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Version history

Date	Version	Description of change	Author
2011-02-28	1.01	Origin	Ligang
2011-5-18	1.02	&5.2 Modified hardware flow control AT command.	

Related documents

SN	Document name	Remark
[1]	TCPIP Application Note	TCPIP Application Note

1 Introduction

This document describes the Serial interface of the modules and how to take it into account in client's application design. This document can help user quickly understand Serial interface of the modules.

2 Connection

SIM900 is designed as a DCE (Data Communication Equipment). It provides a full modem Serial port which is used for data transmission and for sending AT commands. The Serial port Contains data lines TXD and RXD, hardware flow control lines RTS and CTS, status lines DTR, DCD and RI. Serial port interface is available which complies with 2.80 Volts interface.

When the module is used in full modem mode for data transmission, all the signal lines should be connected. The following figure shows the connection between module and client (DTE) in full modem mode

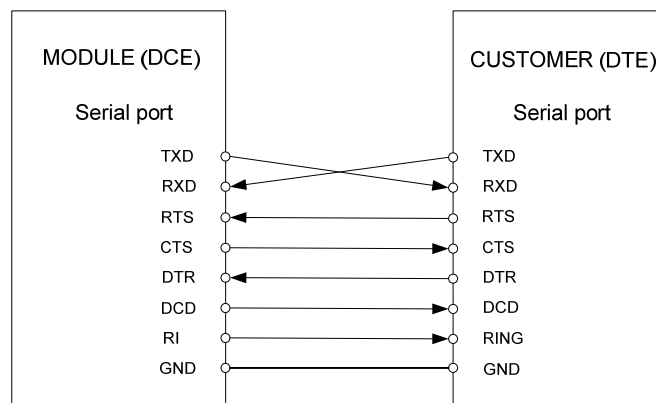


Figure 1: Connection of the serial interfaces in full modem mode

When the module is used in null modem (no handshaking) mode for data transmission, only RXD and TXD are used in user's application, other serial pins should be kept open. The following figure shows the connection between module and client (DTE) in null modem mode.

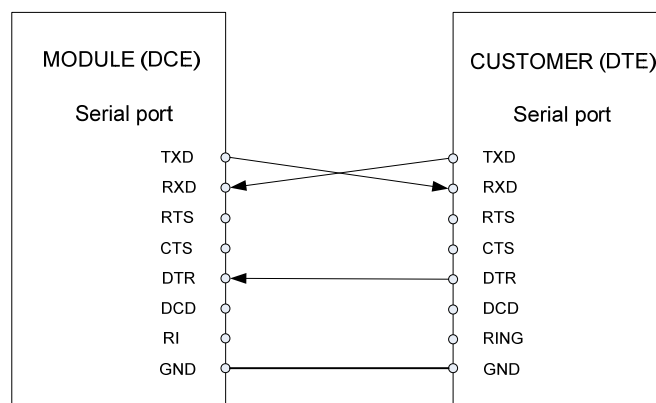


Figure 2: Connection of the serial interfaces in null modem mode

NOTE: The DTR signal must pulled to low level voltage when DTE is sending data to module. If DTR does not connect with DTE, DTR must be connected to GND via a 10K resistor.

3 Level shifter

The significant levels are 0V (for low data bit or ON condition) and 2.80V (for high data bit or OFF condition). For electrical characteristics please refer to the following table.

Table 1: Logic levels of the serial port

Parameter	Min	Max	Unit
V _{IL}	0	0.4	V
V _{IH}	2.4	3.0	V
V _{OL}	0	0.1	V
V _{OH}	2.7	3.0	V

If user's MCU or PC's voltage is out of the range, lever shifter needs to be used.

3.1 Communication with MCU

The module can choose the lever shifter by buffer with open drain outputs (e.g. NC7WZ07) or transistor.

Note:

VDD_EXT is supplied by the module(2.80V), VCC_MCU is voltage of user UART interface

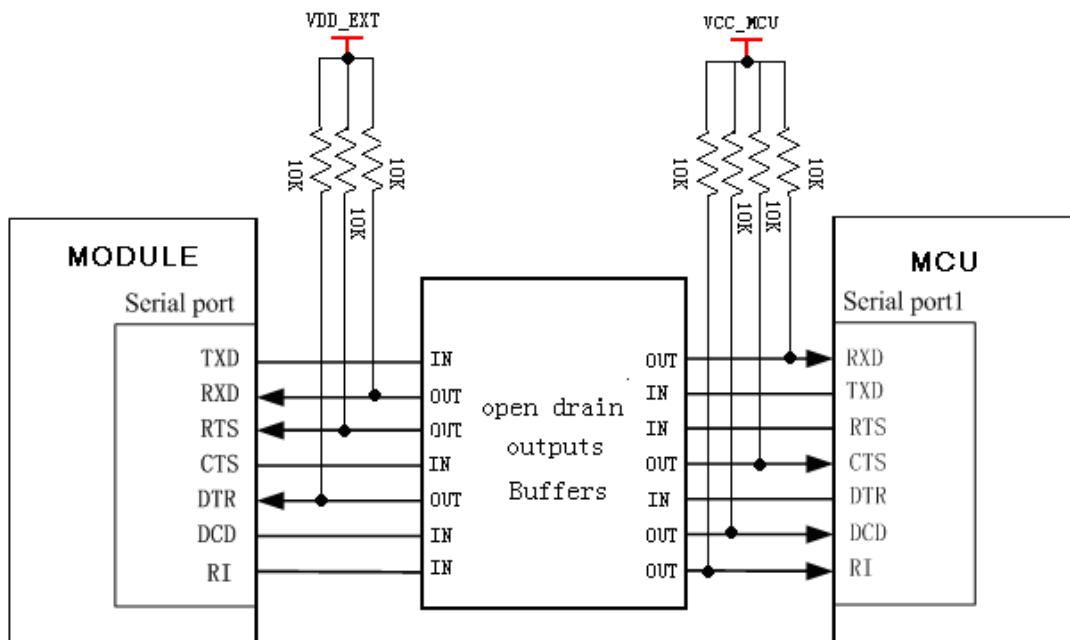


Figure 3: The lever shifter by buffer with open drain outputs

By transistor

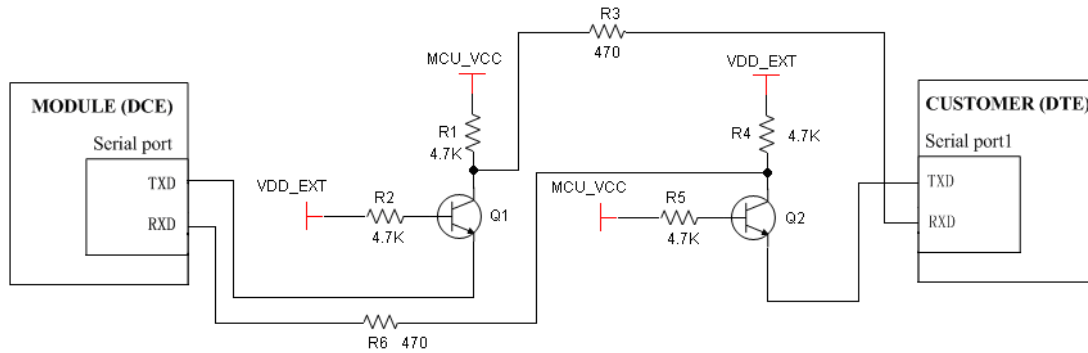


Figure 4: The lever shifter by transistor for communication with MCU

3.2 Communication with PC (RS232)

Table 2: The voltage of RS232

RS232 voltage values		
Level	Transmitter capable (V)	Receiver capable (V)
logic 0	+5 ... +15	+3 ... +25
logic 1	-5 ... -15	-3 ... -25
Undefined	-	-3 ... +3

It is suggested doing the lever shifter by RS-232 transceivers (e.g.SP3238E or MAX3221 etc.)

Connect all signals

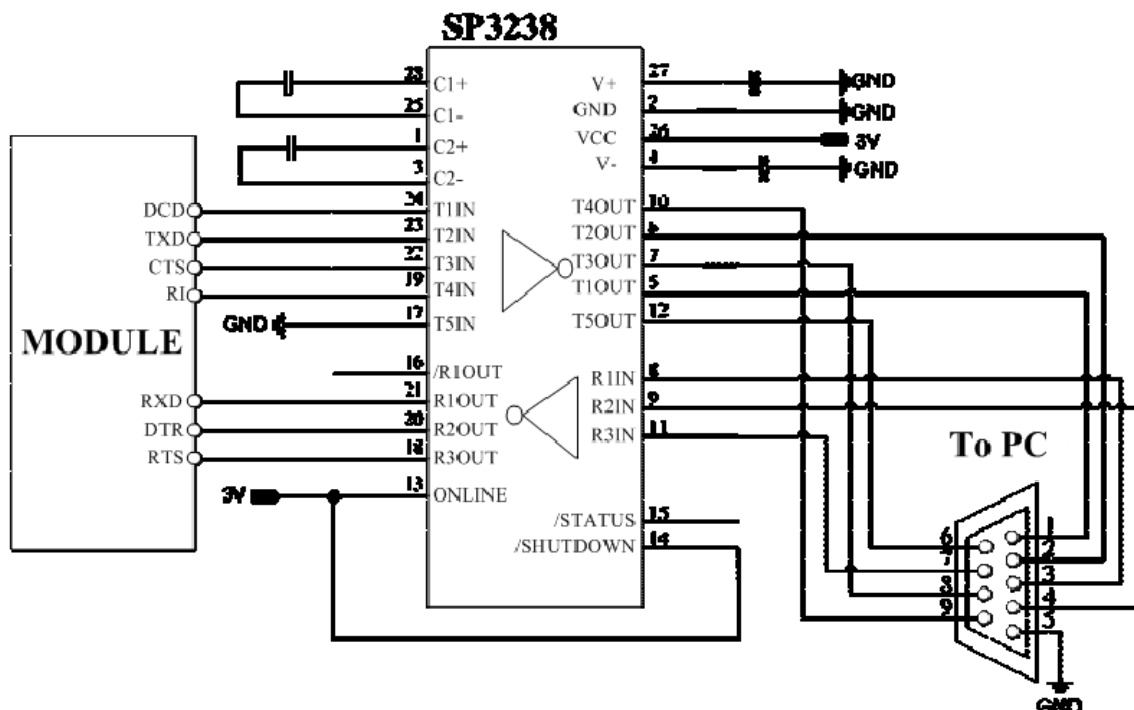


Figure 5: The lever shifter by SP3238E for communication with PC

If just RXD and TXD are connected, MAX3221 can be chosen for the level shifter.

4 Synchronize baud rate

SIM900 is designed in autobauding mode by default. Autobauding allows SIM900 to automatically detect the baud rate of the host device. In application, host device must to synchronize the baud rate with SIM900. Host device must firstly send character “A” to synchronize the baud rate. It is recommended to send “AT” until host device receives the “OK” response, which means host device and SIM900 are correctly synchronized. Once the baud rate is synchronized, it is suggested to use AT command “AT+IPR” to set SIM900 baud rate according the host baud rate. Following figure shows the flow of synchronization of baud rate between SIM900 and host device.

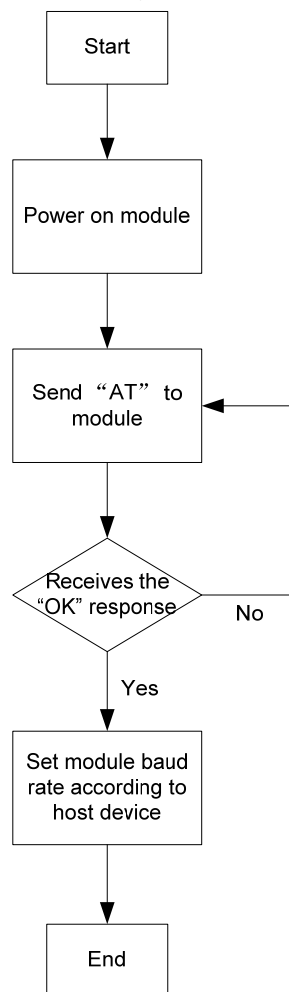


Figure 6: Synchronizing baud rate flow chart

5 Flow control

Flow control is very important for correct communication between the module (DCE) and host device (DTE). In cases of a data or fax call, the sending device is transferring data faster than the receiving side is ready to accept. When the receiving buffer reaches its capacity, the receiving device should be capable to pause the sending device until it catches up.

SIM900 is designed as no flow control by default. The AT command “AT+IFC” can be used to enable the hardware flow control or software flow control, which are basically two approaches to achieve data flow control.

5.1 Software flow control (XON/XOFF flow control)

Software flow control sends different characters to stop (XOFF, decimal 19) and resume (XON, decimal 17) data flow. It is quite useful in some applications that only use three wires on the serial interface.

The AT command “AT+IFC=1,1” can be used to enable software flow control in the DTE interface and within module.

This setting is stored automatically.

Ensure that any communications software package (e.g. ProComm Plus, Hyper terminal or WinFax Pro) uses software flow control.

NOTE:

Software Flow control should not be used for data calls where binary data will be transmitted or received (e.g. TCP/IP) as the DTE interface may interpret binary data as flow control characters.

5.2 Hardware flow control (RTS/CTS flow control)

Hardware flow control achieves the data flow control by controlling the RTS/CTS line. When the data transfer should be suspended, the CTS line is set inactive until the transfer from the receiving buffer has been completed. When the receiving buffer is ok to receive more data, CTS goes active once again.

The AT command “AT+IFC=2,2” can be used to enable hardware flow control in the DTE interface and within module.

This setting is stored automatically.

To achieve hardware flow control, ensure that the RTS/CTS lines are present on user’s application platform.

NOTE: The DTR signal must be pulled to low level voltage when DTE is sending data to the module. Otherwise, the CTS signal may always not be asserted by module and the handshaking will not be established.

6 Control signals

6.1 CTS

This signal is asserted by the module to inform the DTE device that transmission may begin. RTS and CTS are commonly used as handshaking signals to moderate the flow of data into the module.

6.2 RTS

This signal is asserted (low level) to prepare the module (DCE) for accepting transmitted data from the DTE

device.

6.2 DCD

The AT command AT&C can be used to set DCD function mode. When set “AT&C=0”, DCD line is always ON (low). When set “AT&C=1”, DCD line is ON (low) only in the presence of data carrier.

6.3 DTR

Module will automatically go into SLEEP mode (set AT+CSCLK=1) if DTR is set to high level and there is no on air and no hardware interrupt (such as GPIO interrupt or data on serial port). In this case, the current consumption of module will reduce to the minimal level. During SLEEP mode, the module can still receive paging message and SMS from the system normally. If DTR Pin is pulled down to a low level, this signal will wake up module from SLEEP mode. The serial port will be active after DTR changes to low level about 50ms. DTR must be held low during the call.

The AT command “AT&D” can be used to set DTR function mode.

When it is set to “AT&D0”, TA ignores status on DTR.

When it is set to “AT&D1”, ON (low)->OFF (high) on DTR: module will be changed to command mode when the connected call is remained..

When it is set to “AT&D2”, ON->OFF on DTR: call is disconnected, module is changed to Command mode. During state DTR = OFF, it is auto-answer off.

TCP/IP applications only support AT&D1 and AT&D0. In TCP/IP application (for more detail, please refer to TCP/IP application NOTE), DTR line of serial port can also be used to switch from data mode to command mode. To use this method, AT&D1 should be set firstly. Pull DTR line to ground for at least 1 second and then pull up, the module will switch from data mode to command mode and OK will be returned which indicates the module is in command mode.

6.4 RI

If the module is used as caller, the RI will maintain high. But when it is used as receiver, the responses of RI are listed in the following table.

Table 3: RI responds

State	RI respond
Standby	HIGH
Voice calling	Change to LOW, then: (1) Change to HIGH when call is established. (2) Use AT command ATH, the RI pin is changed to HIGH. (3) Sender hangs up, change to HIGH. (4) SMS received
Data calling	Change LOW, then: (1) Change to HIGH when call is established. (2) Use AT command ATH, the RI is changed to HIGH.

SMS	When receiving SMS, The RI will be changed to LOW and hold at low level for about 120 ms, then it is changed to HIGH.
URC	<p>Following URCs triggers 120ms low level on RI.</p> <p>UNDER-VOLTAGE WARNNING</p> <p>OVER-VOLTAGE WARNNING</p> <p>+CEXTHS:</p> <p>+CEXTBUT:</p> <p>RING</p> <p>Call Ready</p> <p>+CBMT:</p> <p>+CMTI:</p> <p>+CMT:</p> <p>+TSMSINFO:</p> <p>+SMREADY:</p> <p>+CDS:</p>

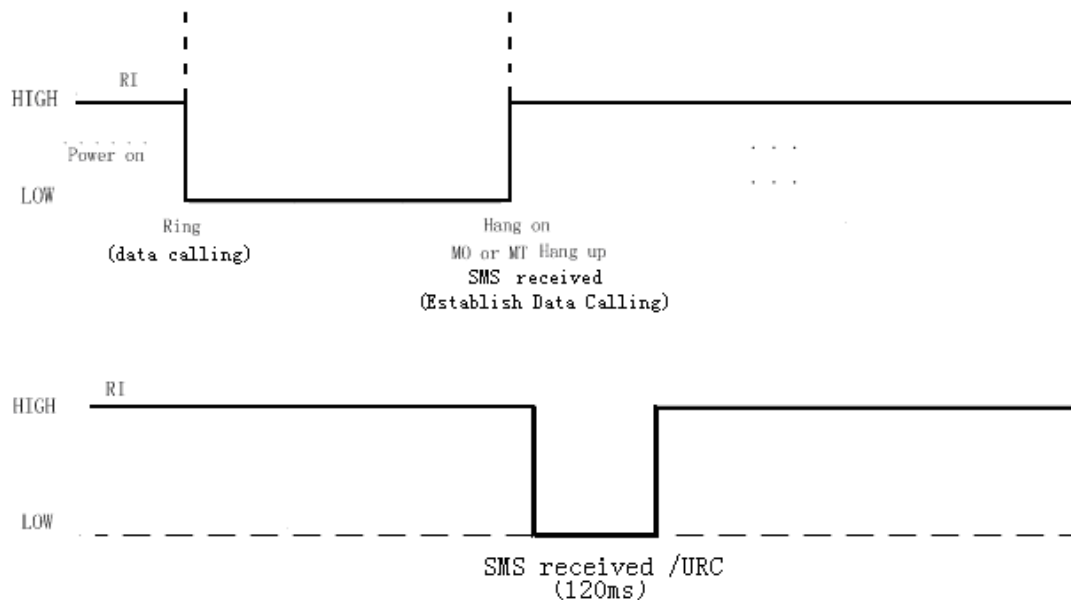


Figure 7: Behaviors of RI

Table 4: AT+CFGRI Indicate RI when using URC

Read command AT+ CFGRI ?	Response : +CFGRI: <status> ok
	Parameter: See set command
Set Command AT+ CFGRI=<status>	Response : OK
	Parameter: <status> 0 on 1 off
Reference	Note

We suggest that you connect the RI to an interrupt port of MCU. It can be used for waking up from power saving mode. That means the MCU will receive an interrupt while a falling edge coming on RI.

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